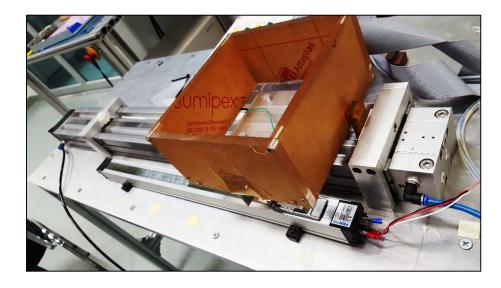
NEUMATIC ISTON OSITION



C

O

N

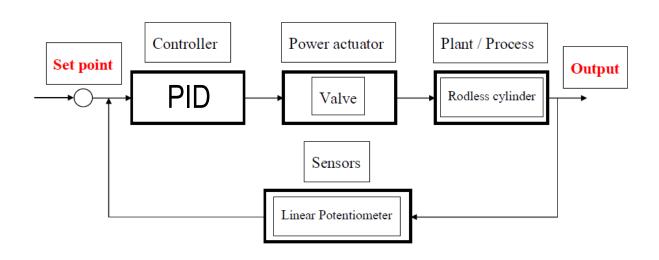
T

R

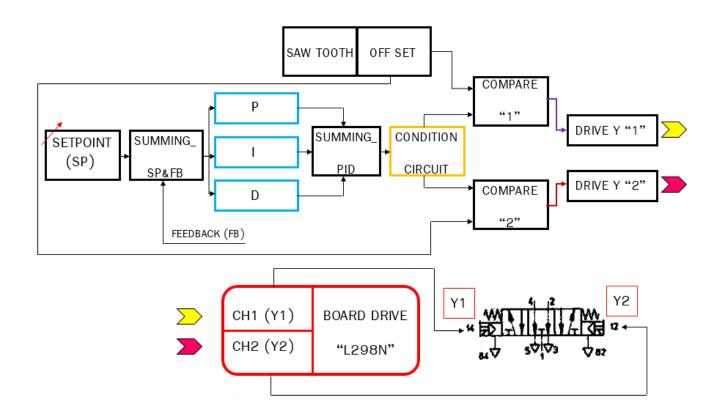
O

L

STRUCTURE OF PNEUMATIC POSITION CONTROL

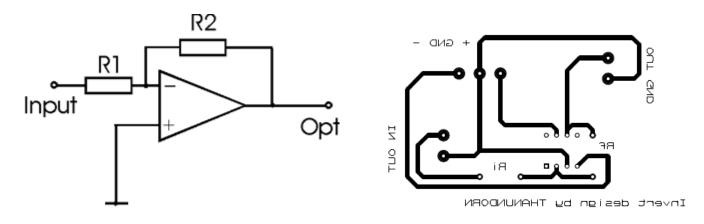


PID CONTROLLER & OTHER CIRCUIT FOR
SUPPORT PROCESS (ELECTRONICS CIRCUIT
BOARD)

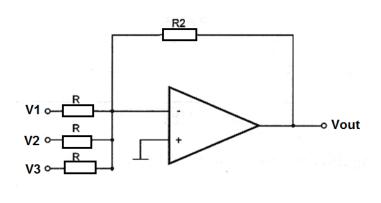


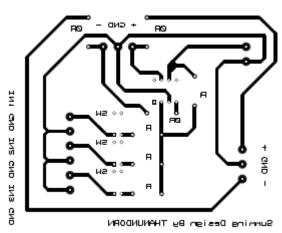
DETAILS OF THE VARIOUS CIRCUIT —

USE "INVERT OP AMP" FOR SET POINT

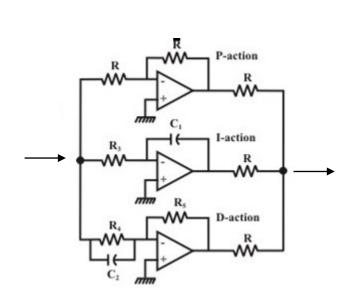


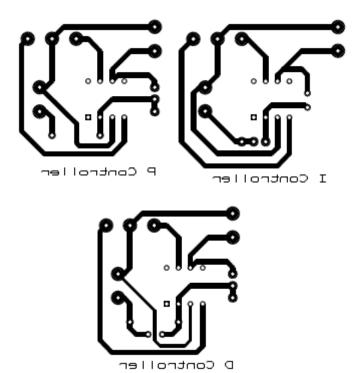
USE "SUMMING OP AMP" FOR SUMMING_SP&FB, SUMMING_PID



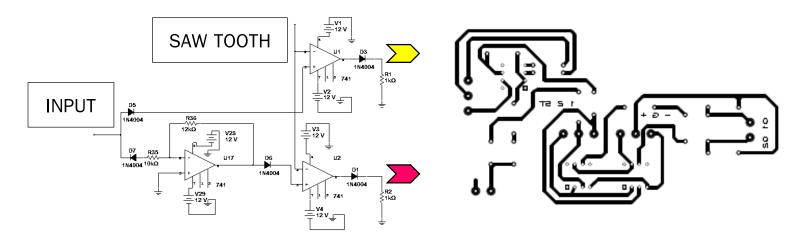


USE "PID CIRCUIT" FOR P,I,D





"1", COMPARE "2"



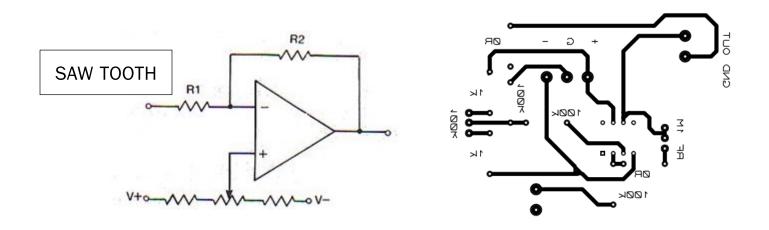
REMARK:

- IF INPUT IS NEGATIVE SIGNAL (BY PID), PINK
 SIGNAL "ON" FOR CREATE PWM SIGNAL WITH SAW TOOTH
 SIGNAL
- IF INPUT IS POSITIVE SIGNAL (BY PID), YELLOW SIGNAL "ON" FOR CREATE PWM SIGNAL WITH SAW TOOTH SIGNAL

USE "IC XR2206" FOR SAW TOOTH

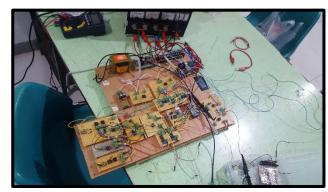
XR-2206 XR-

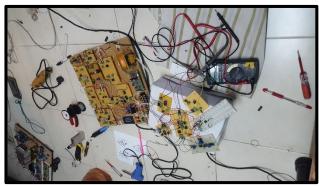
USE "OFF SET OP AMP" FOR OFF SET

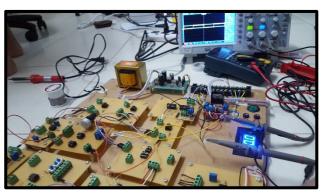


LAUNCH PROCESS & TEST BOARD

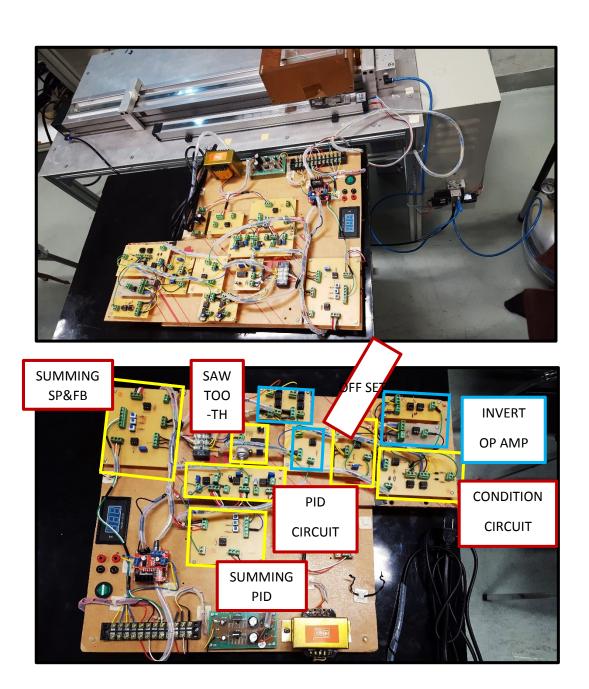




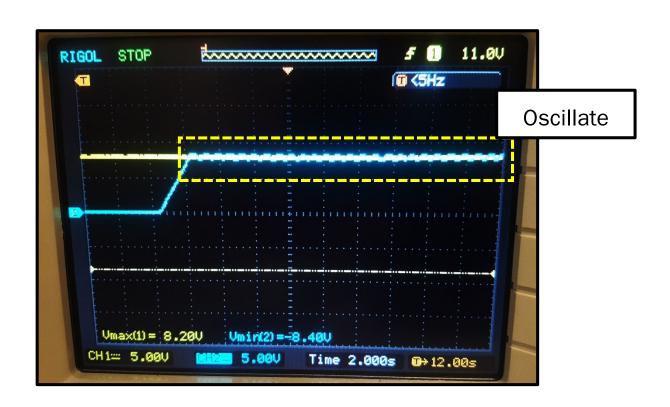




FINISHED FOR MAKE CONTROL BOARD



FIRST STEP: CONTROL PLANT WITH BOARD CONTROL WITHOUT PID CONTROLLER

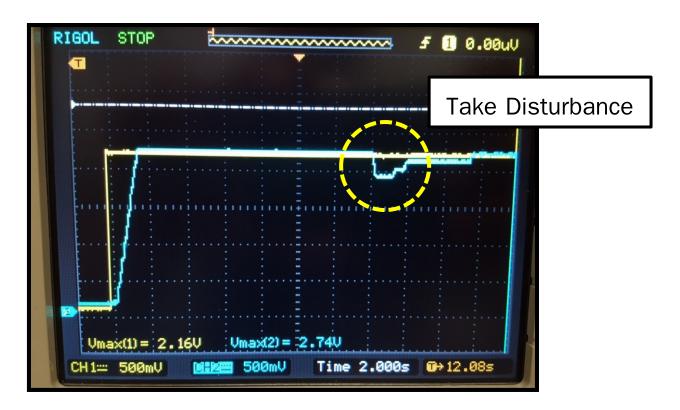


LINK ON YOUTUBE:

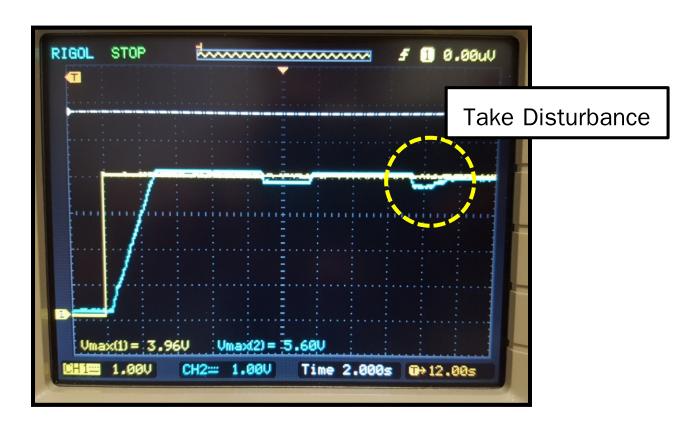
https://www.youtube.com/watch?v=0w9gn3PvptY&feature=youtu.be

SECOND STEP: CONTROL PLANT WITH BOARD CONTROL WITH PID CONTROLLER

SET POINT = 2 CM



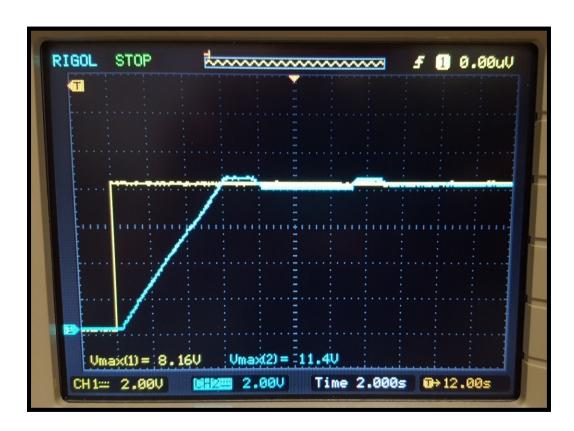
SET POINT = 4 CM



SET POINT = 6 CM



SET POINT = 8 CM



SET POINT = 10 CM



LINK ON YOUTUBE:

https://www.youtube.com/channel/UCk-_PIO-SpOCo8RCGlb2Plw/videos?sort=dd&shelf_id=0&view=0

CONCLUDE EXPERIMENT!

When experiment finished, I found Pneumatic (piston) position control that can control by electronics device with PID controller system, although process use air in to moving position cylinder, which air can subside but PID controller can control position be success. In a position that want to control.

If you want to watch to VDO other in this project you can search "Thanundorn Yamsual" on Youtube or lower the this sheet.

And If you want "User Manual" you can download at uppermost. (Thai Language)